

Lecture 16

Panel Data Models (III)

- Non-linear Panel Models -

Read { Greene WP (Survey paper)
Panel RE Models Review in Stata
Survey paper by Amelano & Donore

Panel Modelling (as we know)

i) FE $y_{it} = \beta' x_{it} + \alpha_i + \varepsilon_{it}$

ii) RE $y_{it} = \beta' x_{it} + u_{it}, u_{it} = \alpha_i + \varepsilon_{it}$

iii) Random Parameters* $y_{it} = \beta_i' x_{it} + \varepsilon_{it}, \beta_i = \beta + v_i, E(v_i) = 0, \text{Var}(v_i) = \Sigma$

$\Rightarrow y_{it} = (\beta + v_i)' x_{it} + \varepsilon_{it} = \beta' x_{it} + u_{it}, u_{it} = v_i' x_{it} + \varepsilon_{it}$

.. groupwise heteroskedastic model; somewhat restrictive

eg) $\log L_i = \sum_t \log \Phi \left(\beta_i' x_{it} \right)$
 $\frac{1}{1 + X_i' \Sigma X_i}$

(1) Nonlinear Models with Fixed Effects

$$\log \mathcal{L} = \sum_{i=1}^N \sum_{t=1}^{T_i} \log g(y_{it}, \beta' x_{it} + \alpha_i, \theta)$$

$$\frac{\partial \log \mathcal{L}}{\partial \beta} = 0, \quad \frac{\partial \log \mathcal{L}}{\partial \alpha_i} = 0 \quad (i=1, \dots, N), \quad \frac{\partial \log \mathcal{L}}{\partial \theta} = 0$$

incidental parameter problem!

Another key problem: $\hat{\beta}$ is a function of $\hat{\alpha}_i$, while $\hat{\alpha}_i$ is biased when T_i is small. Thus, $\hat{\beta}$ becomes biased!

$$\text{Var}(\hat{\alpha}_i) = O(T_i^{-1}) \Rightarrow \text{Var}(\hat{\beta}) = O(T_i^{-1})$$

Note "A sequence c_T is of order T^d , denoted $O(T^d)$ if $\lim_{T \rightarrow \infty} \frac{1}{T^d} c_T$ is a finite non-zero constant."

eg) $\text{Var}(\hat{\beta}) \frac{1}{T_i^{-1}} = T_i \cdot \text{Var}(\hat{\beta}) \rightarrow \text{something}$

Note "A sequence c_T is of order less than T^d , denoted $o(T^d)$ if $\lim_{T \rightarrow \infty} \frac{1}{T^d} c_T$ equals 0."

* Conditioning-out Method for FE Models

there are a few cases where the conditional density provide consistent estimator of β .

then, the conditional likelihood function is not a function of α_i .

examples

i) FE logit model

" $\sum_t y_{it}$ is a sufficient statistic "

the conditional density, conditional on $\sum_{t=1}^{T_i} y_{it}$, is free of α_i .

ii) FE Poisson model

$$\log L = \sum_i \sum_t \left[-\exp(\alpha_i) \exp(\beta'X_{it}) + y_{it}(\beta'X_{it} + \alpha_i) \right]$$

$$\frac{\partial \log L}{\partial \alpha_i} = -\exp(\alpha_i) \sum_t \left[\exp(\beta'X_{it}) + \sum_t y_{it} \right] \Rightarrow \text{can be ignored}$$

$$\Rightarrow \exp(\alpha_i) = \frac{\sum_t y_{it}}{\sum_t \exp(\beta'X_{it})}$$

plug this into log L to obtain the concentrated likelihood function.

then, it is free of α_i .

this also works for neg. binomial models.

iii) Cox-proportional duration model

(not panel, but adopts a similar idea)

Note this method does not work for probit and Tobit models. It works for linear exponential conditional mean equations.

Read Greene WP (p. 14)

Also, Maddala book, p. 215.

(2) Nonlinear Models with Random Effects

$f(y_{it}, \dots, y_{iT_i}, u_i)$

$$Q_i = f(y_{i1}, \dots, y_{iT_i}) = \int f(y_{i1}, \dots, y_{iT_i} | u_i) f(u_i) du_i$$

$$= \int \prod_{t=1}^{T_i} f(y_{it} | u_i) f(u_i) du_i$$

Three cases

i) Exact integration & closed form

Poisson regression with a gamma density
 $f(y_{it} | u_i)$ $f(u_i)$

"this works for a cross-sectional count model as well."

ii) Approximation by Hermite quadrature

Butler & Moffitt's (1982) method, using a normal density $f(u_i)$: earlier note

$$\int \prod_{t=1}^{T_i} f(y_{it} | u_i) f(u_i) du_i$$

$$= \frac{1}{\sigma u \sqrt{2\pi}} \int_{-\infty}^{\infty} \prod_{t=1}^{T_i} g(y_{it}, \beta'x_{it} + u_i, \theta) \exp\left(-\frac{u_i^2}{2\sigma^2}\right) du_i$$

$$= \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \prod_{t=1}^{T_i} g(y_{it}, \beta'x_{it} + \sigma v_i, \theta) \cdot \frac{1}{\sqrt{\pi}} \exp(-v_i^2) dv_i$$

$$= \sum_{h=1}^H w_h \prod_{t=1}^{T_i} g(y_{it}, \beta'x_{it} + \sigma z_h, \theta)$$

where z_h & w_h are nodes and weights for the Hermite quadrature of degree H .

Applications : RE probit^(logit), RE poisson (also neg bin, intreg)
 RE Tobit, RE Selection, ...
 (almost all RE models & PA models) "population average"

iii) Simulated Maximum Likelihood

$$\int \prod_{t=1}^{T_i} f(y_{it}|u_i) \cdot f(u_i) du_i$$
$$= E \left[\prod_{t=1}^{T_i} f(y_{it}|u_i) \right] = E[F(u_i|\theta)]$$

If (u_{i1}, \dots, u_{iR}) is a random sample of iid draws from multi-variate distributions, then

$$\text{then } \frac{1}{R} \sum_{i=1}^R F(u_{ir}|\theta) = E[F(u_i|\theta)]$$

the simulated integral can be inserted into the likelihood function. then do MLE.

Note . How many R should be used is a question.
Does it produce the same results as in the exactly integrated counterpart.
see references (wv, p. 18)

(3) Generalized Equation Estimation (GEE) ; STATA covers this!

Also called Generalized Linear Models (GLM)

by McCullagh & Nelder (1983) -- popular in other applied sciences

GEE (GLM) fits generalized linear models of y

$$g\{E(y)\} = X\beta, \quad y \sim F$$

i) $g(\cdot)$ is the canonical link

ii) $F \sim$ distribution

eg) $E(y) = X\beta, \quad y \sim \text{Normal}$

link = identity, $F \sim \text{normal}$

5

eg2) $\text{logit}\{E(y)\} = X\beta$, $y \sim \text{Bernoulli}$

$\log\left[\frac{E(y)}{1-E(y)}\right]$

link: logit function

F: Bernoulli

eg3) $\log(E(y)) = X\beta$, $y \sim \text{Poisson}$

link: log function $\leftarrow E(y) = \exp(X\beta)$

F: Poisson

eg4) $E^{-1}(E(y)) = X\beta$, $y \sim \text{Bernoulli}$

link: inverse Gaussian cumulative.

Estimation: Iterative weighted LS using the generalized estimating equation.

For details, see McCullagh & Nelder (1983)

Note: i) The method is extended from the quasi-score function by Wedderburn (1974).

ii) there may be many possible links, and there are no theoretical justifications.

(see Greene, WP. p25)

Only a few links make sense.

eg. count data model

: only log-transformation appears proper
probit or logit links do not make sense.]

"advantage" \Rightarrow iii) In panel models, group correlations can be modeled. "xtgee" in stata)

$\text{Cov}(z_{it}, z_{is}) = \rho_{ts}$

(4) Latent Class Models (LIMDEP Version 8.0)
covers this!

Express

$$f(y_{it}) = \sum_{j=1}^M p_j g(y_{it}, \beta'x_{it} + \alpha_j, \sigma) \quad \text{Not } \alpha_i. \quad : M \text{ latent classes!}$$

where $0 \leq p_j \leq 1, \sum_j p_j = 1$

point: If there are heterogeneity, heterogeneous groups can be divided by M groups. Then the distribution is given as a MIXTURE of distributions with different parameters (α_j).

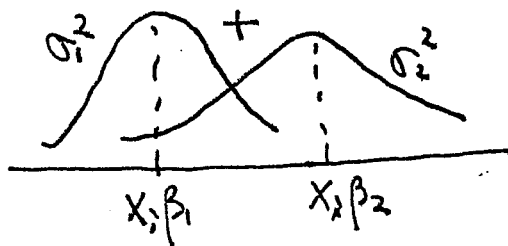
Note A regime switching model is a special case of such treatment. (M=2)
 (Quandt & Ramsey (1978): regime switching
 (Maddala & Nelson (1975): disequilibrium model)

$$y_i = \begin{cases} x_i \beta_1 + e_{i1} & \text{with prob } \lambda \\ x_i \beta_2 + e_{i2} & \text{with prob } 1-\lambda \end{cases}$$

$$f(y_i) = \lambda \cdot \frac{1}{\sigma_1} \phi\left(\frac{y_i - x_i \beta_1}{\sigma_1}\right) + (1-\lambda) \frac{1}{\sigma_2} \phi\left(\frac{y_i - x_i \beta_2}{\sigma_2}\right)$$

heterogeneous parameters in this example = (β_1, β_2) & (σ_1^2, σ_2^2)

⇒



: weighted average of two mixtures of distributions. (weight = λ)

Note In a cross-sectional model, the unobserved heterogeneity can be modeled as α_j ... firstly suggested by Heckman & Singer (1984)
: duration models

Example) Probit Model : Keane & Geweke (1999)

$$y_i = \mathbb{1}(\beta'x_i + \varepsilon_i > 0)$$

$$f(\varepsilon_i) = \sum_{j=1}^M p_j \frac{1}{\sigma_j} \phi\left(\frac{\varepsilon_i - \mu_j}{\sigma_j}\right)$$

(parameters : p_j, μ_j, σ_j)

$$P(y_i=1) = \int_{-\beta'x_i}^{\infty} \left[\sum_{j=1}^M p_j \left(\frac{1}{\sigma_j}\right) \phi\left(\frac{\varepsilon_i - \mu_j}{\sigma_j}\right) \right] d\varepsilon_i$$

Note $\sum_{j=1}^M p_j = 1$ need to be satisfied.

We can consider

$$p_j = \frac{e^{\theta_j}}{\sum_{j=1}^M e^{\theta_j}} \quad j=1, \dots, M, \quad \theta_M = 0 \text{ (normalization)}$$

- we may write $\theta_j = \gamma_j' z_i$ (dependent on z_i)

- In panel

$$p_{ij} = \frac{e^{\theta_{ij}}}{\sum_{j=1}^M e^{\theta_{ij}}}, \quad j=1, \dots, M, \quad \theta_M = 0$$

Estimation MLE, E-M algorithm

$$\frac{\partial \ln L}{\partial p} = 0 \Rightarrow p_j \text{ is a function of } \hat{\beta} \quad \text{iterates!}$$

$$\frac{\partial \ln L}{\partial \beta} = 0 \Rightarrow \hat{\beta} \quad \text{"} \quad p_j$$

Summary of Nonlinear Panel data Models

"INT" "Integrating out" method (Gauss-Hermite quadrature)
 "CONT" "Conditioning out" method (Conditional likelihood)
 "SML" simulated ML.

| | <u>FE</u> | <u>RE</u> | <u>SML</u> | <u>Latent class (LIMDEP)</u> | <u>GEE (STATA)</u> |
|-------------------------|------------------------|----------------------------|------------------------|------------------------------|--------------------|
| (1) Probit | dummy (inconsistent) | INT | | ✓ | ✓ |
| (2) Logit | CONT | INT | | ✓ | ✓ |
| (3) Poisson | CONT | INT | | ✓ | ✓ |
| (4) Neg Bin | CONT | INT | | ✓ | ✓ |
| (5) TOBIT (Truncation) | dummy * (inconsistent) | INT | ✓ (truncation) | ✓ | • |
| (6) SELECTION | dummy * (inconsistent) | - | ✓ | ✓ | • |
| (7) Interval Regression | - | INT | | ✓ | • |
| (8) Multiple Responses | - | INT (ordered logit/probit) | ✓ (multinomial probit) | • | • |
| (9) Frontier | dummy (inconsistent) | INT | | ✓ | • |

Note Some recent developments are discussed in the survey paper. they include semi-parametric methods.